

On the Coverability Problem for Pushdown Vector Addition Systems in One Dimension

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Vector Addition Systems – Recap

Definition

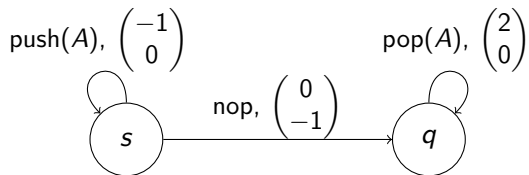
A VAS is a finite set of vectors $\mathbf{a} \in \mathbb{Z}^d$. For $\mathbf{v}, \mathbf{v}' : \mathbb{N}^d$ it has a step

$$\mathbf{v} \xrightarrow{\mathbf{a}} \mathbf{v}' \quad \text{if} \quad \mathbf{v}' = \mathbf{v} + \mathbf{a}.$$

- ▶ Equivalent to Petri Nets
(concurrency, weak counters, event systems)
- ▶ Reachability: decidable
Mayr'81, Kosaraju'82, . . . Leroux and Schmitz'15
- ▶ Coverability, Boundedness: EXPSPACE-complete
Lipton'76, Rackoff'78
- ▶ Most Games/Equivalences undecidable (e.g. Bisimulation)
Jančar'95

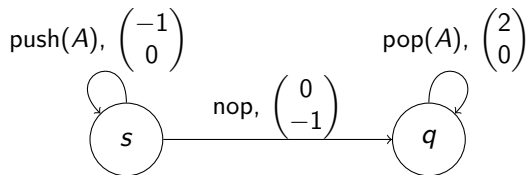
Pushdown Vector Addition Systems

... are products of VAS with pushdown automata.



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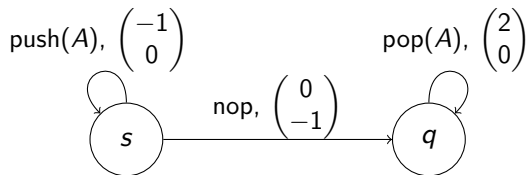
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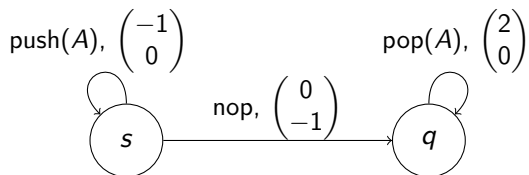
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$$s, \perp, \begin{pmatrix} 2 \\ 1 \end{pmatrix} \longrightarrow \longrightarrow s, AA\perp, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

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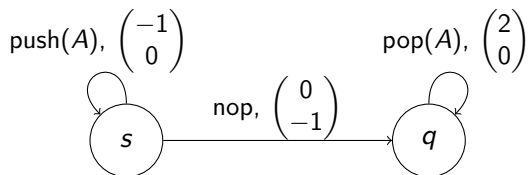
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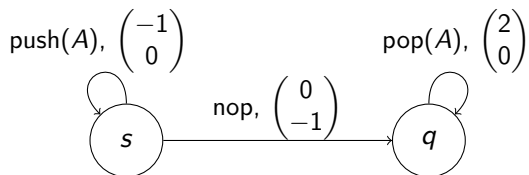
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Pushdown Vector Addition Systems

... are products of VAS with pushdown automata.



- ▶ Reachability = Coverability: decidability open
TOWER-hard *Lazic'13*
- ▶ Boundedness: decidable with Hyper-Ackermannian bounds
Leroux, Praveen, and Sutre'14

Pushdown Vector Addition Systems

Observation

Reachability in dim. d reduces to Coverability in dim. $d + 1$.

$$\text{Reach}(0) \rightsquigarrow \text{Cover}(1) \rightsquigarrow \text{Reach}(1) \rightsquigarrow \text{Cover}(2) \rightsquigarrow \dots$$

Our Contribution

Coverability for 1-dimensional Pushdown VAS is decidable.

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Another Perspective

Given:

- ▶ a VAS $\mathbf{A} \subset \mathbb{Z}^d$
- ▶ a context-free language $L \in \mathbf{A}^*$
- ▶ vectors $\mathbf{s}, \mathbf{t} \in \mathbb{N}^d$

Question: are there $\mathbf{a}_1 \mathbf{a}_2 \dots \mathbf{a}_k \in L$ and $\mathbf{t}' \geq \mathbf{t}$ with

$$\mathbf{s} \xrightarrow{\mathbf{a}_1} \xrightarrow{\mathbf{a}_2} \dots \xrightarrow{\mathbf{a}_k} \mathbf{t}' \quad ?$$

Grammar-Controlled Vector Addition Systems

Definition (GVAS)

A CfG $G = (V, A, R)$ where $A \subseteq \mathbb{Z}$.

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The *summary* of a nonterminal of $X \in V$ is

$$\text{SUMMARY}_X(\mathbf{s}) \stackrel{\text{def}}{=} \sup\{\mathbf{t} \mid \mathbf{s} \xrightarrow{X} \mathbf{t}\}$$

Coverability:

$$\text{SUMMARY}_X(\mathbf{s}) \geq \mathbf{t} ?$$

Example: Ackermann Functions $A_m : \mathbb{N} \rightarrow \mathbb{N}$

$$A_m(n) \stackrel{\text{def}}{=} \begin{cases} n + 1 & \text{if } m = 0 \\ A_{m-1}^{n+1}(1) & \text{if } m > 0 \end{cases}$$

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$$X_2 \vdash -\mathbf{1} X_2 X_1 \mid \mathbf{1} X_1$$

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$$A_m = \text{SUMMARY } X_m$$

$$(\text{via } X_m \xrightarrow{*} -\mathbf{1}^n X_m X_{m-1}^n \implies -\mathbf{1}^n \mathbf{1} X_{m-1}^{n+1} \xrightarrow{*} \dots)$$

Flow Trees

Certificates for $\text{SUMMARY}_S(c) \geq d$? Derivation trees!

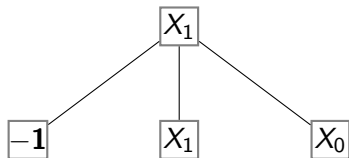
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X_1

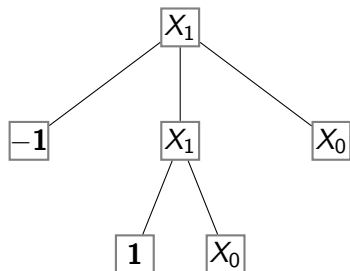
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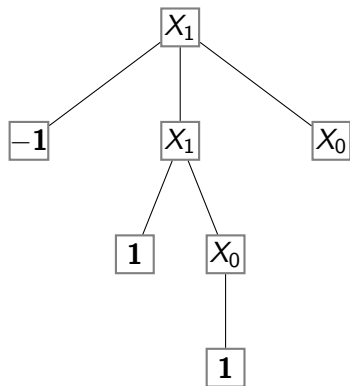
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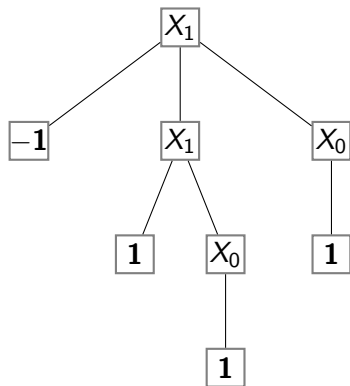
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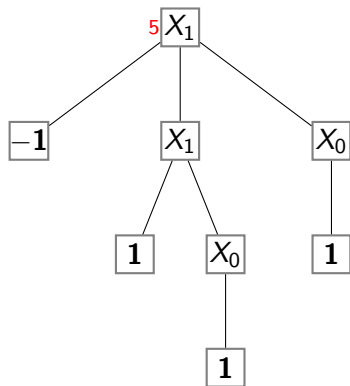
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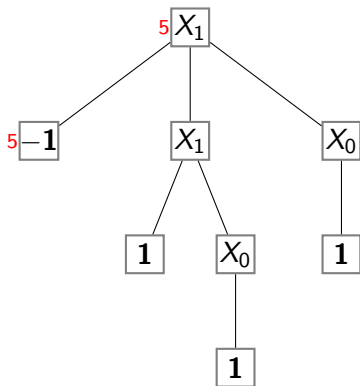
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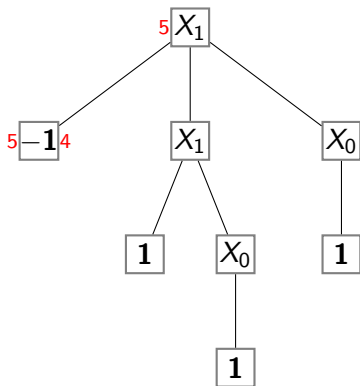
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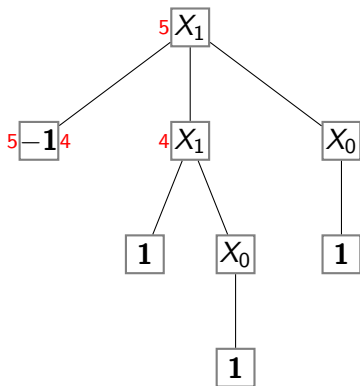
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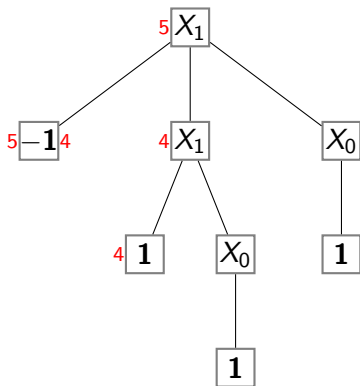
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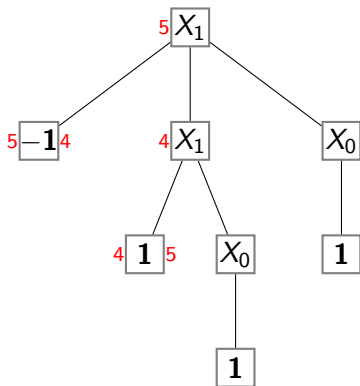
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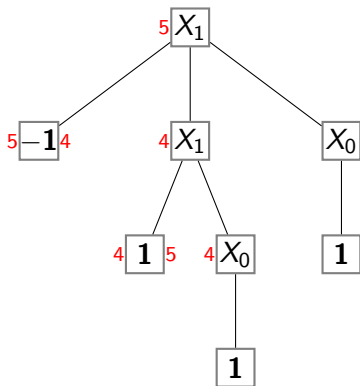
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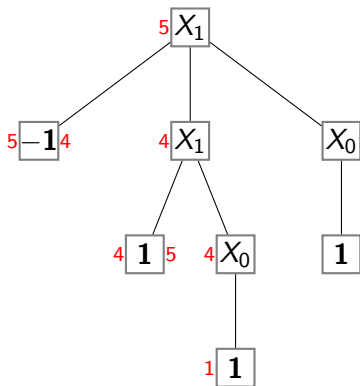
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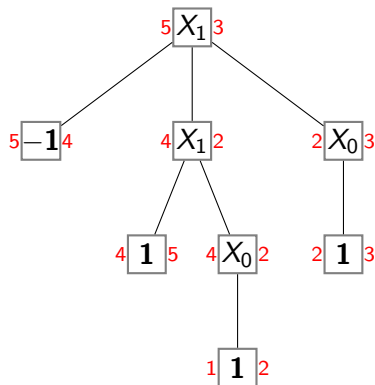
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Flow Trees

Certificates for $\text{SUMMARY}_S(c) \geq d$? Derivation trees!



Flow Conditions

1. Nodes satisfy $\text{SUMMARY}_X(IN) \geq OUT$
2. Labelling of neighbouring nodes is consistent

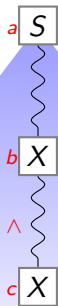
Flow Trees . . . can be arbitrarily large!



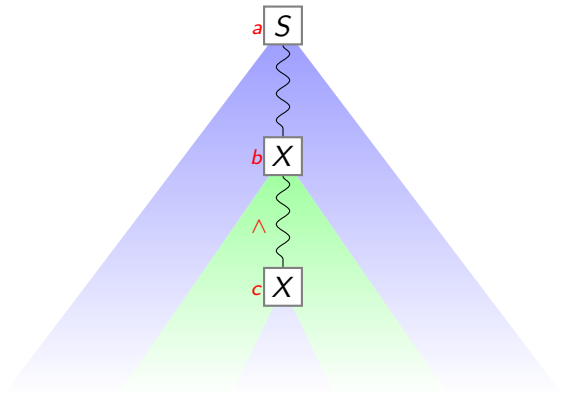
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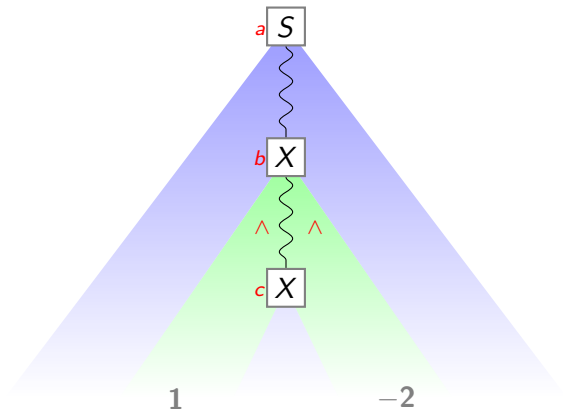
Pruning Flow Trees



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$$\text{RATIO}_X \stackrel{\text{def}}{=} \liminf_{n \rightarrow \infty} \frac{\text{SUMMARY}_X(n)}{n}$$

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Grammar for A_m

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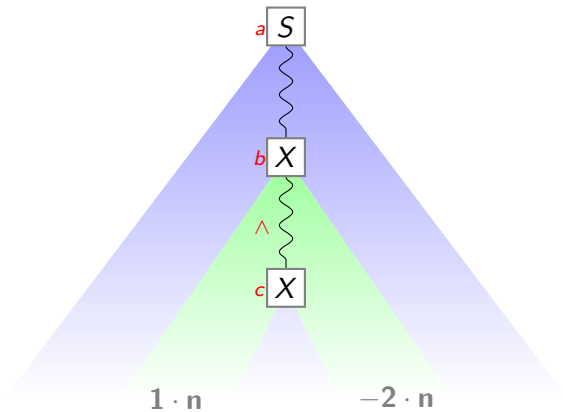
$$\text{RATIO}_{X_0} = 1$$

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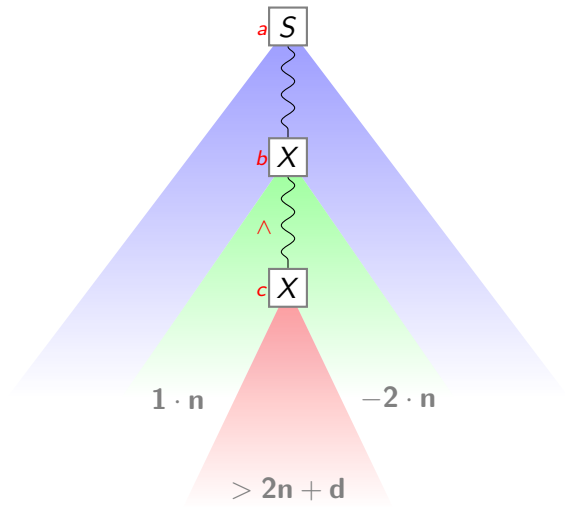
$$\text{RATIO}_{X_2} = 2$$

$$\text{RATIO}_{X_3} = \infty$$

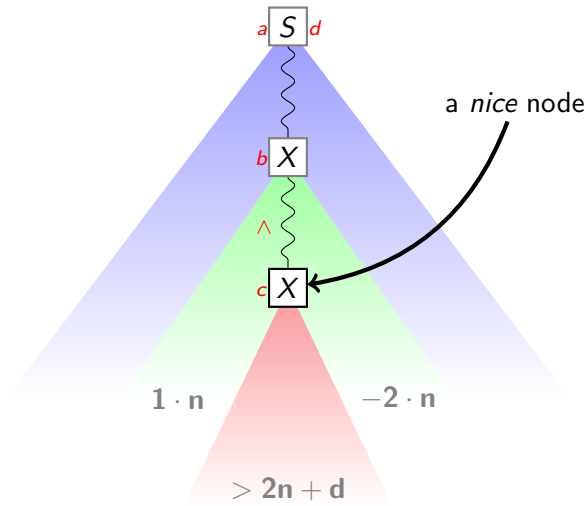
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Main Argument for Decidability

Def.: A *Certificate*

is a flow tree where every leaf is either nice or has a finite ratio.

We show that

1. $c \xrightarrow{S} d' \geq d$ implies a small certificate with root $c \boxed{S} d$.
2. it is possible to check if $\text{RATIO}_X = \infty$
3. if $\text{RATIO}_X < \infty$, then SUMMARY_X is computable

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Conclusion

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- ▶ Grammar-Controlled VAS, flow trees. . .
- ▶ Complexity (dim. 1)
 - ▶ Coverability: NP-hard; in EXPSPACE (?)
 - ▶ Boundedness: NP-hard; in EXPTIME .
- ▶ In arbitrary dimension d :
 - ▶ Reachability=Coverability: open
 - ▶ Boundedness: decidable; TOWER-hard; in \mathbf{F}_{ω^d}

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Questions?