Branching-Time Model Checking Gap-Order Constraint Systems

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September 26, 2013

The Model			References
Gap Cl	auses		

Def: Gap Clauses

$$x - y \ge k$$

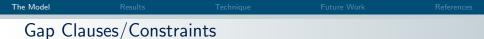
where x, y are integer variables or constants and $k \in \mathbb{Z}$.

The Model			
Gap CI	auses/Constra	aints	

Def: Gap Constraints

$$\bigwedge_{1\leq i\leq n} (x_i - y_i \geq k_i)$$

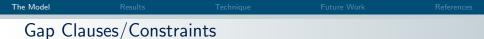
where x_i, y_i are integer variables or constants and $k_i \in \mathbb{Z}$.



Def: positive Gap Constraints

$$\bigwedge_{0 \le i \le n} (x_i - y_i \ge k_i)$$

where x_i, y_i are integer variables or constants and $k_i \in \mathbb{N}$.

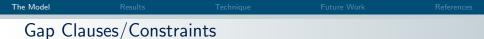


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positive GC are not negation-closed!



Def: positive Gap Constraints

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0

positive GC are not negation-closed!

Write

 $Var = \{x, y, ...\} \text{ for the variables}$ $Const \subset \mathbb{Z} \text{ for the constants and}$ $Val \text{ for the set of valuations } \nu : Var \to \mathbb{Z}.$

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Gap Co	onstraints		

can characterise subsets S ⊆ Val (of satisfied valuations)
 can determine how valuations evolve:

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Gap Co	onstraints		

can characterise subsets S ⊆ Val (of satisfied valuations)
 can determine how valuations evolve: For instance,

$$x-x'\geq 0$$

means the value of x does not increase.

The Model Results Technique Future Work References

Gap-Order Constraint Systems

Definition (CGS)

are given by finite sets

Var of variables ranging over \mathbb{Z} ,

Const of integer constants, and

 Δ of *positive* transitional gap contraints.

Gap-Order Constraint Systems

Definition (CGS)

 $\nu \longrightarrow \nu'$ iff $\nu \oplus \nu' \models C$ for some $C \in \Delta$.

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$$u \oplus
u'(x) = \begin{cases}
\nu(x), & \text{if } x \in Var \\
\nu'(x), & \text{if } x \in Var'.
\end{cases}$$

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 Gap-Order Constraint Systems

Definition (CGS)

$$\nu \longrightarrow \nu'$$
 iff $\nu \oplus \nu' \models C$ for some $C \in \Delta$.

Example:

$$\begin{array}{l} \mathcal{C}_1 = (x-x' \geq 1) \land (y'-y \geq 0) \land (y-y' \geq 0) \land (x'-0 \geq 0) \\ \mathcal{C}_2 = (y-y' \geq 1) \land (x'-x \geq 0) \land (y'-0 \geq 0) \end{array}$$

Gap-Order Constraint Systems

Definition (CGS)

$$\nu \longrightarrow \nu'$$
 iff $\nu \oplus \nu' \models C$ for some $C \in \Delta$.

Example:

$$\begin{aligned} \mathcal{C}_1 &= (x > x' \ge 0) \land (y' = y) \\ \mathcal{C}_2 &= (x \le x') \land (y > y' \ge 0) \end{aligned}$$

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 Gap-Order Constraint Systems

Definition (CGS)

$$\nu \longrightarrow \nu'$$
 iff $\nu \oplus \nu' \models C$ for some $C \in \Delta$.

Example:

lex. Countdown of
$$(y, x)$$

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The Model				
Overapp	roximating (Counter Mach	ines	

 $\begin{array}{l} {\sf Zero-tests} \\ (c_1-0\geq 0) \wedge (0-c_1\geq 0) \end{array}$

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Overappro	oximating (Counter Mach	ines	

Zero-tests $(c_1 = 0)$

The Model	Results	Technique	Future Work	References
Overap	proximating (Counter Mach	ines	
Zero-t	ests			
1	•			

 $(c_1 = 0)$

Finite Control $(state = 0) \land (state' = 1)$ $// s_0 \longrightarrow s_1$

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Overapp	roximating (Counter Mach	ines	

Zero-tests			
$(c_1 = 0)$			

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Increments/Decrements

 $(c_1' - c_1 \ge 0)$ // c_1 ++

The Model				
Overapp	proximating (Counter Mach	nines	

Zero-tests
$$(c_1 = 0)$$

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 $egin{array}{lll} (c_1'-c_1\geq 0)& //c_1++\ (c_1-c_1'\geq 0)\wedge (c_1'-0\geq 0)& //c_1- \end{array}$

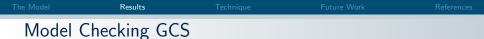
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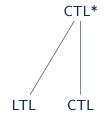
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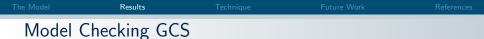
Increments/Decrements are imprecise!

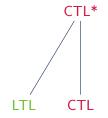
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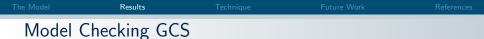


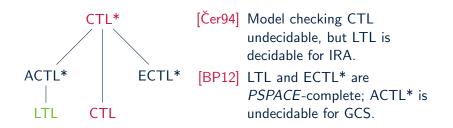
[Čer94] Model checking CTL undecidable, but LTL is decidable for IRA.

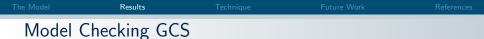


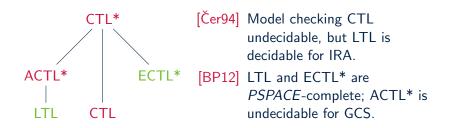


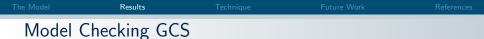
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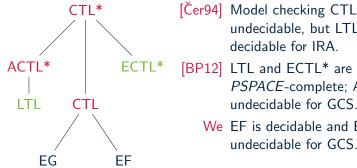






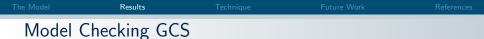


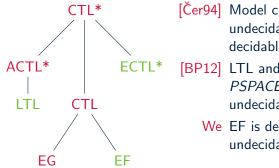




undecidable. but LTL is decidable for IRA. [BP12] LTL and ECTL* are PSPACE-complete; ACTL* is undecidable for GCS.

> We EF is decidable and EG undecidable for GCS.





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The Model		Results		Technique		Future Wor	k	References
CTL	over G	ap Cla	auses					
Syn	tax							
,	$\psi ::= \mathcal{C} \mid$	$\neg\psi\mid$	$\psi \lor \psi \mid$	$X\psi \mid$	$EF\psi \mid$	$EG\psi$	$\mid (\psi U\psi)$	

The Model	Model Results		Technique		Future Work		References
EG (over Gap	Clauses					
Syr	ntax						
	$\psi ::= \mathcal{C} \mid$	$\neg\psi \mid \ \psi \lor \psi$	$\mid X\psi \mid$	FF/ #/ N	$EG\psi$	/X/X44/ U 14/X	



Syntax

- EG model checking GCS is undecidable.
- Proof by enforcing exact increments/decrements (Simulating Minski machines).

The M	odel	Results	Technique		Future Work		References
E	F over Ga	p Clauses					
	Syntax						
	$\psi ::= \mathcal{C} \mid$	$\neg\psi\mid \psi\vee\psi\mid$	$X\psi \mid$	$EF\psi \mid$	ÆĢ⋪¢	/X/X44/ U 14/X	



Syntax

$\psi ::= \mathcal{C} \mid \neg \psi \mid \psi \lor \psi \mid X\psi \mid EF\psi \mid \not E\mathcal{G}/\psi \quad //(\langle \psi / \mathcal{U}/ \psi / \mathcal{V}))$

- EF model checking GCS is decidable.
- Proof by finding finite representation for Sat(C) that is closed under negation, union, Pre and Pre*.

$$egin{aligned} \mathcal{C} =& (x-0 \geq 1) \ \wedge (y-0 \geq 0) \ \wedge (0-y \geq 0) \end{aligned}$$

 \sim





Degree of MG: inverse of minimal negative value



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- Closure of MG has same denotation



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 Monotonicity Graphs

 Gap Constraints as finite labeled graphs over Var U Const



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$$\psi ::= \mathcal{C} \mid \psi \lor \varphi \mid \neg \psi \mid X\psi \mid EF\psi$$

	Technique	
Negation		

 $Rep(S) = \{M_0, M_1, \ldots, M_k\}$

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 $\mathcal{C}_{M_0} \vee \mathcal{C}_{M_1} \vee \cdots \vee \mathcal{C}_{M_k}$

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... is a Gap-Formula in DNF.

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$$\sim$$

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... is a Gap-Formula in DNF.

→ propagate negations to clauses
 → negate clauses ← increases degree

$$x-y \not\geq k \iff y-x \geq -(k-1)$$

 $\ \, \stackrel{\longrightarrow}{\rightarrow} \ \, \text{bring to DNF} \\ \ \, \stackrel{\longrightarrow}{\rightarrow} \ \, \text{interpret as set of MG}$

The Model	Results	Technique	Future Work	References
Computing	Pre			
$S = \{ \nu \mid \nu \}$	$(x) > \nu(y) =$	0}		

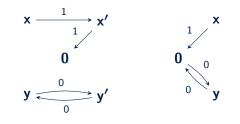
		Technique	
Computi	ng <i>Pre</i>		

$$S = \{ \nu \mid \nu(x) > \nu(y) = 0 \}$$



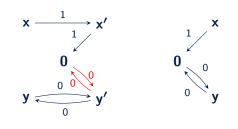
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$$\begin{array}{l} S \ = \{\nu \ | \ \nu(x) > \nu(y) = 0\} \\ \mathcal{C}_1 = (x - x' \geq 1) \land (y' - y \geq 0) \land (y - y' \geq 0) \land (x' - 0 \geq 0) \end{array}$$



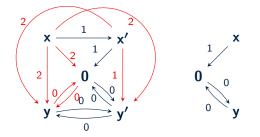
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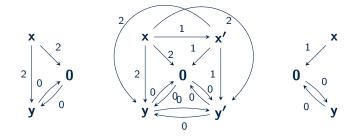
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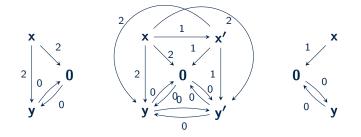
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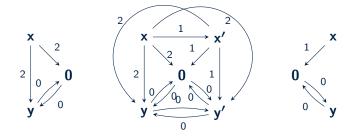


 $Pre(C_1, S)$

S

		Technique	
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 $Pre(C_1, S)$

NB: Degree does not increase

S

		Technique	
Computing	Pre*		

 $M \sqsubseteq M'$ if $M(x, y) \le M'(x, y)$ for all $x, y \in Var \cup Const$.

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- **2** \sqsubseteq is a well-order over MG^n

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Computing	Pre*		

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- **1** $M \sqsubseteq M'$ implies $\llbracket M \rrbracket \supseteq \llbracket M' \rrbracket$
- **2** \sqsubseteq is a well-order over MG^n

Compute $Pre^*(M)$:

iteratively unfold the finite! backwards coverability tree and take the union of all nodes...

The Model

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EF Model Checking GCS is decidable

Theorem

For given GCS and EF formula φ , the set $Sat(\varphi)$ is effectively Gap-definable.

The Model

EF Model Checking GCS is decidable

Theorem

For given GCS and EF formula φ , the set $Sat(\varphi)$ is effectively Gap-definable.

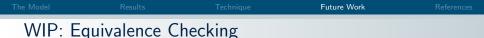
Works even with

- arbitrary gap-formulae as atoms and
- positive (trans.) gap-constraints on X/EF operators.

			Future Work	
WIP: E	Equivalence Ch	necking		

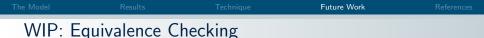
Bisimulation

- $GCS \approx FS$ is decidable using char. formulae in EF
- Strong Bisimulation $GCS \sim GCS$ is undecidable



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- Strong Bisimulation $GCS \sim GCS$ is undecidable
- 2 Trace inclusion/equivalence
 - $GCS \subseteq GCS$ is in EXPSPACE
 - Universality is EXPSPACE-hard



1 Bisimulation

- $GCS \approx FS$ is decidable using char. formulae in EF
- Strong Bisimulation GCS ~ GCS is undecidable
- 2 Trace inclusion/equivalence
 - $GCS \subseteq GCS$ is in EXPSPACE
 - Universality is EXPSPACE-hard
- 3 Simulation Preorder
 - $GCS \leq FS$ and vv. are decidable (wqo)
 - GCS \leq GCS ? WIP.

		References
References		

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