Principles of Computer Game Design and Implementation

Lecture 28

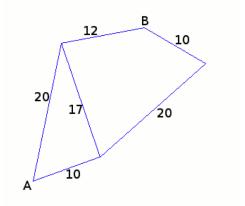
Outline for today

• Pathfinding 2

Tackling Paths

- Characters "live" in a computer world
 - Even developers may not know exact location
 - Physics simulations

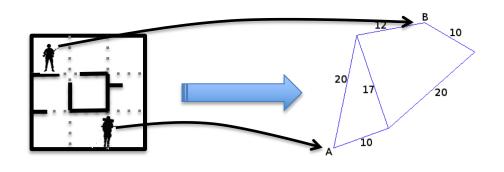




• Pathfinders operate on discrete structures

World Representation

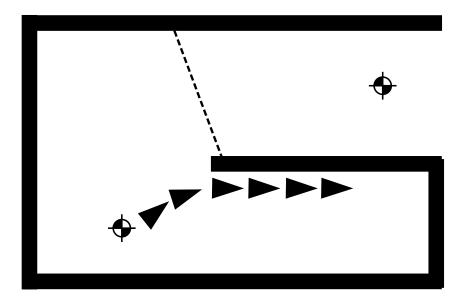
To use pathfinding



- Division Scheme
 - Quantisation and Localisation
 - Converting positions into nodes and back
 - Generation
 - Who and how define the mapping
 - Validity
 - Being able to fulfil the plan

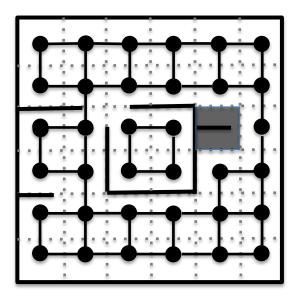
Bad Quantisation

• Errors in quantisation can lead to invalid plans



• Plans have to agree with steering

Tile-Based Graphs



• tileX = (int) (x/tileSize)
tileY = (int) (y/tileSize)

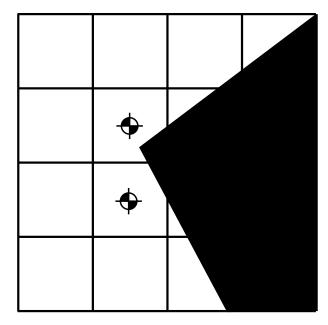
Works in square worlds

Tile-Based Graphs: Validity

• If wall are not parallel to tiles

• Will steering succeed?





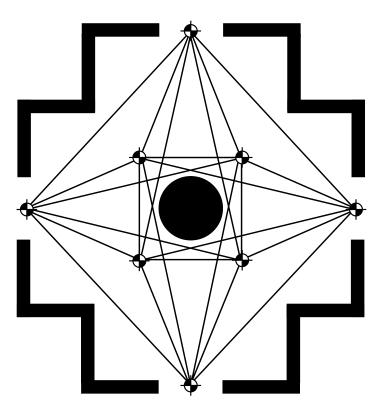
Waypoints

Locations on map + edges

- Identified by designers
- Computed automatically
 - Corner waypoints
 - Points of visibility

Popular game AI technique

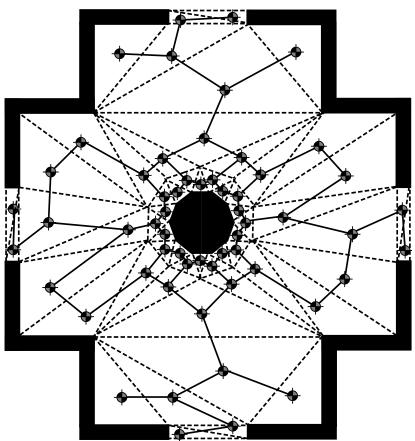
• Half-life



Navigation Mashes

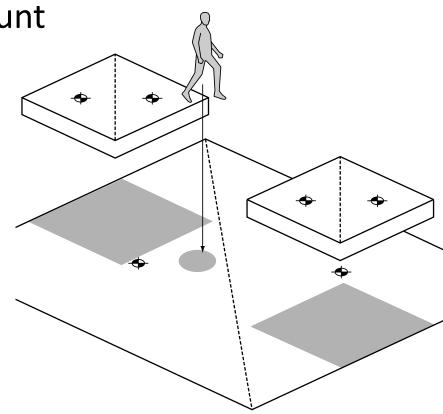
In modern games models are built from polygons (triangles)

- A character can always pass between adjacent polygons
- Fully automated generation of graphs



Correct Quantisation

- Several levels in the model
 - Take elevations into account when mapping to a graph node

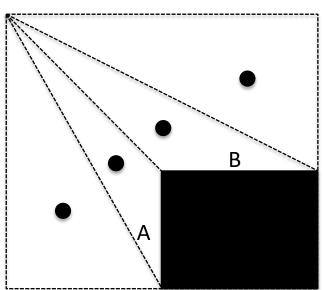


Validity of Plans

 Character can always pass between adjacent polygons

 No direct pass between A and B

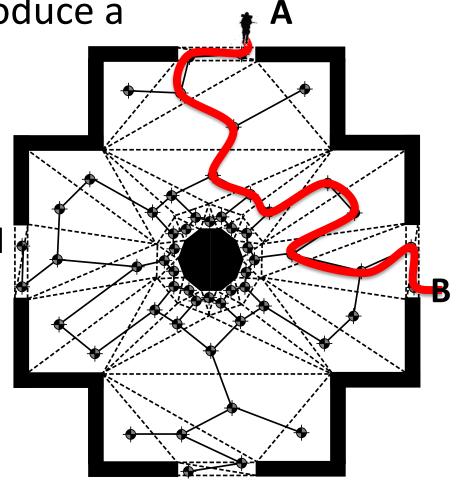
 Floor plan is done by designers and they avoid this



Chunky Paths

 Pathfinding may not produce a natural movement

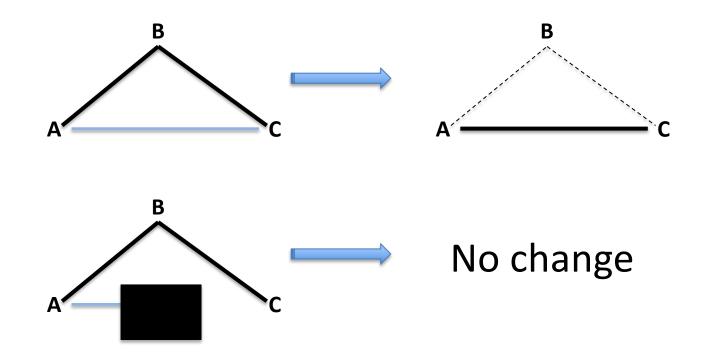
After a path is found
It needs to be smoothed



String Pulling

• Move **A** – **B** – **C**

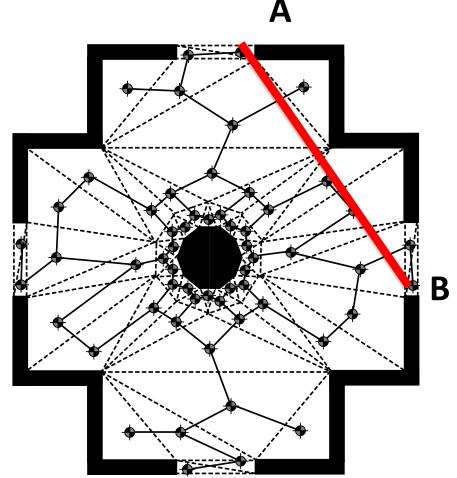
- If C can be seen from A, drop B



Example

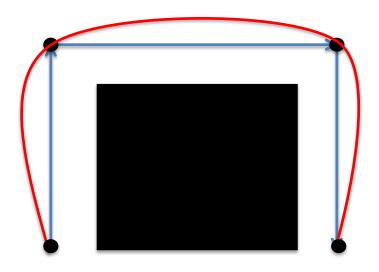
• Extreme case

 Even if there are obstacles, string pulling gives better paths



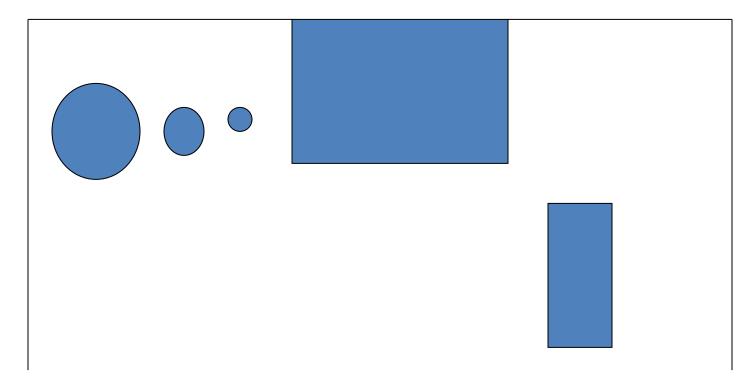
Splines

- Chunky paths can be further smoothed by converting them to *splines*
 - Curves that *approximate* paths
 - Some maths required (see wikipedia)



Passable Edges

• Not every agent can pass



• Need to adapt graphs for agents

Following Paths

We assume that if a move is planned it can be executed

- Validity of a division scheme

What is the world changes

– Other agents move about?

Possible Solutions

- Leave space between agents
 - Different pathfinding graphs for different agents

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- Centralised pathfinding
- May not be natural (e.g. tanks)
- Assume there is no path

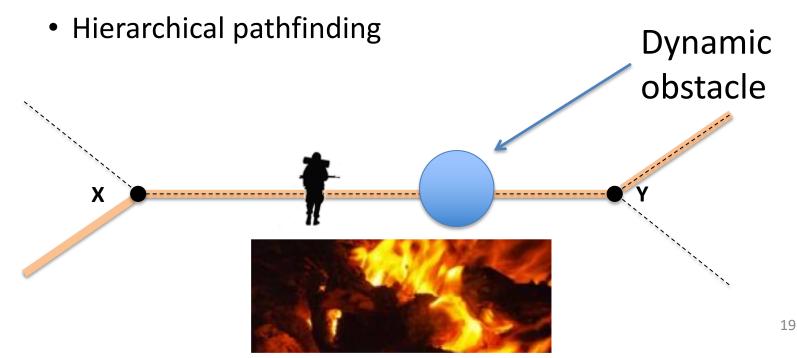
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• Navigate around the obstacle

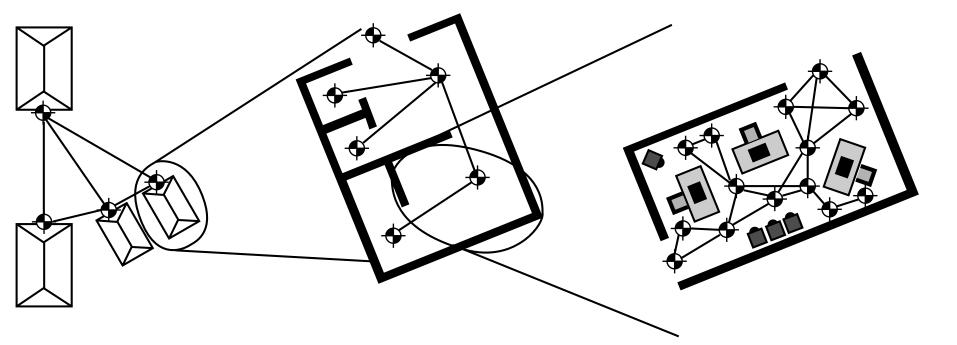
– Steering / Pathfinding

Beware of the Pit

- Pathfinder requires to move X → Y
 - Steering can fail
 - Navigation meshes are much better
 - Easier to re-plan (full information about passable areas)



Hierarchical Pathfinding



May not discover shortest path

Other Pathfinding Topics

- Cooperative pathfinding
 - Finding a path for a group of agents
- Variable terrain cost
 - Penalise paths near existing units
- Pathfinding using the GPU
- Pathfinding in dynamic environments
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Pathfinding: Summary

- Algorithmically, not very difficult
 - $-A^*$
 - Choice of heuristics is important
 - Do not fear inadmissible heuristics!
- Linking model and graph can be tricky
 - A number of methods
 - Trend towards navigational meshes
 - Some developers disagree
- Paths often require smooting